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STATISTICS COLLOQUIUM

MONDAY, FEBRUARY 1, 2016
TALK: 4:15 PM — SCIENCE CENTER 300H
RECEPTION: 3:50 PM

**“Inference for Dynamic and Latent Variable Models
via Iterated, Perturbed Bayes Maps”**

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ABSTRACT

Iterated filtering algorithms are stochastic optimization procedures for latent variable models that recursively combine parameter perturbations with latent variable reconstruction. Previously, theoretical support for these algorithms has been based on the use of conditional moments of perturbed parameters to approximate derivatives of the log likelihood function. We introduce a new theoretical approach based on the convergence of an iterated Bayes map. A new algorithm supported by this theory displays substantial numerical improvement on computational challenges for inferring parameters of a partially observed Markov process.